

## MODULE II: GRAM-SCHMIDT

## Linear Algebra 4: Orthogonality & Symmetric Matrices and the SVD

### TOPIC 1: The Gram-Schmidt Process

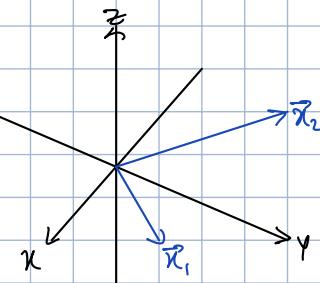
Motivation: Suppose  $\vec{v}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$  and  $\vec{v}_2 = \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix}$ .

$\vec{v}_1$  and  $\vec{v}_2$  are linearly independent  $\Rightarrow$  they form a basis for  $W = \text{Span}\{\vec{v}_1, \vec{v}_2\}$ ,  
but  $\vec{v}_1$  and  $\vec{v}_2$  do not give an orthogonal basis for  $W$ .

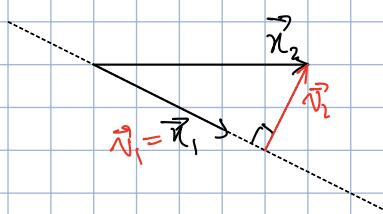
How might we construct an orthogonal basis for  $W$ ?

Example: Let  $W$  be the subspace of  $\mathbb{R}^3$  spanned by  $\vec{v}_1$  and  $\vec{v}_2$ . Construct an orthogonal basis for  $W$ .

$$\vec{v}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \quad \vec{v}_2 = \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix}$$



$\vec{v}_2$  is a linear combination of  $\vec{v}_1$  and  $\vec{v}_2$ .



$$\begin{aligned} \text{Set } \vec{v}_1' &= \vec{v}_1, \quad \vec{v}_2' = \vec{v}_2 - \text{proj}_{\vec{v}_1'} \vec{v}_2 \\ &= \vec{v}_2 - \frac{\vec{v}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 \\ &= \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} - \frac{2}{2} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} \end{aligned}$$

$\therefore$  our orthogonal basis is  $\{\vec{v}_1', \vec{v}_2'\}$ .

### The Gram-Schmidt Process with Two Vectors

Suppose we are given a set of vectors  $\{\vec{v}_1, \vec{v}_2\}$  in  $\mathbb{R}^n$ . We can construct an orthogonal basis,  $\{\vec{v}_1', \vec{v}_2'\}$  for the space that they span,  $W$ , with the following process:

$$\begin{aligned} \vec{v}_1' &= \vec{v}_1 \\ \vec{v}_2' &= \vec{v}_2 - \frac{\vec{v}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 \end{aligned}$$

We can show that if  $\{\vec{v}_1, \vec{v}_2\}$  are independent, then  $\{\vec{v}_1', \vec{v}_2'\}$  is an orthogonal basis for  $W$ :

\*  $\vec{v}_1'$  and  $\vec{v}_2'$  are in  $W$ .

\*  $\vec{v}_1'$  and  $\vec{v}_2'$  span  $W$ .

\*  $\vec{v}_1'$  and  $\vec{v}_2'$  are orthogonal:  $\vec{v}_1' \cdot \vec{v}_2' = 0$ .

Exercise:

Vectors  $\vec{u}$  and  $\vec{v}$  form a basis for  $W$ .

$$\vec{u} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}, \quad \vec{v} = \begin{pmatrix} 4 \\ 2 \\ -2 \end{pmatrix}$$

Suppose we want to construct an orthogonal basis for  $\mathcal{W}$ , which we will denote by the vectors  $\hat{u}$  and  $\hat{v}$ . If we apply the Gram-Schmidt process to identify an orthogonal basis for  $\mathcal{W}$ , we can set:

$$\hat{u} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

The other vector in our orthogonal basis is:  $\vec{v} - \text{proj}_{\hat{u}} \vec{v} =$

$$\hat{v} = \begin{pmatrix} x_1 \\ x_2 \\ -3 \end{pmatrix}$$

$$\vec{v} = \vec{u}$$

Find  $x_1$  and  $x_2$ .

$$\begin{aligned} \vec{v} - \text{proj}_{\hat{u}} \vec{v} &= \vec{v} - \frac{\vec{v} \cdot \hat{u}}{\hat{u} \cdot \hat{u}} \hat{u} \\ &= \vec{v} - \frac{4+4-2}{1^2+2^2+1^2} \hat{u} = \vec{v} - \vec{u} \end{aligned}$$

$$\vec{v} - \text{proj}_{\hat{u}} \vec{v} = \begin{pmatrix} 3 \\ 0 \\ 3 \end{pmatrix}. \quad \therefore x_1 = 3, x_2 = 0.$$

Example:

The vectors below span a subspace  $\mathcal{W}$  of  $\mathbb{R}^4$ . Construct an orthogonal basis for  $\mathcal{W}$ .

$$\vec{x}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix}, \quad \vec{x}_2 = \begin{pmatrix} 0 \\ 1 \\ 2 \\ 1 \end{pmatrix}, \quad \vec{x}_3 = \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix}$$

Set  $\vec{v}_1 = \vec{x}_1$ ,  $\vec{w}_1 = \text{Span}\{\vec{v}_1\}$

$$\begin{aligned} \vec{v}_2 &= \vec{x}_2 - \text{proj}_{\vec{w}_1} \vec{x}_2 \\ &= \vec{x}_2 - \frac{\vec{x}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 = \vec{x}_2 - \frac{0+1+2+0}{1+1+1+0} \vec{v}_1 \\ &= \vec{x}_2 - \vec{v}_1 \end{aligned}$$

$$\vec{v}_2 = \begin{pmatrix} -1 \\ 0 \\ 1 \\ 1 \end{pmatrix}$$

Check:  $\vec{v}_1 \cdot \vec{v}_2 = 0$ . Set  $\vec{w}_2 = \text{Span}\{\vec{v}_1, \vec{v}_2\}$

$$\begin{aligned} \vec{v}_3 &= \vec{x}_3 - \text{proj}_{\vec{w}_2} \vec{x}_3 \\ &= \vec{x}_3 - \left( \frac{\vec{x}_3 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 + \frac{\vec{x}_3 \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2 \right) \\ &= \vec{x}_3 - \left( \frac{0}{3} \vec{v}_1 + \frac{-1}{3} \vec{v}_2 \right) = \vec{x}_3 + \frac{1}{3} \vec{v}_2 \end{aligned}$$

$$\vec{v}_3 = \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix} + \begin{pmatrix} -1/3 \\ 0 \\ 1/3 \\ 1/3 \end{pmatrix} = \begin{pmatrix} -1/3 \\ 1 \\ -2/3 \\ 1 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} -1 \\ 3 \\ -2 \\ 1 \end{pmatrix}$$

$\Rightarrow$  orthogonal basis for  $\mathcal{W}$  is  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$

## The Gram-Schmidt process

Suppose  $\{\vec{v}_1, \dots, \vec{v}_p\}$  are a basis for a subspace  $W$  of  $\mathbb{R}^n$ .

$$W_1 = \text{Span}\{\vec{v}_1\}$$

$$\vec{u}_1 = \vec{v}_1$$

$$W_2 = \text{Span}\{\vec{v}_1, \vec{v}_2\}$$

$$\vec{u}_2 = \vec{v}_2 - \text{proj}_{W_1} \vec{v}_2$$

$$W_3 = \text{Span}\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$$

$$\vec{u}_3 = \vec{v}_3 - \text{proj}_{W_2} \vec{v}_3$$

$$\vdots$$

$$W_p = \text{Span}\{\vec{v}_1, \dots, \vec{v}_p\}$$

$$\vec{u}_p = \vec{v}_p - \text{proj}_{W_{p-1}} \vec{v}_p$$

Then,  $\{\vec{u}_1, \dots, \vec{u}_p\}$  is an orthogonal basis for  $W$ .

The Gram-Schmidt process can also be written this way.

$$\vec{u}_1 = \vec{v}_1$$

$$\vec{u}_2 = \vec{v}_2 - \frac{\vec{v}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1$$

$$\vec{u}_3 = \vec{v}_3 - \frac{\vec{v}_3 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \frac{\vec{v}_3 \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2$$

$\vdots$

$$\vec{u}_p = \vec{v}_p - \frac{\vec{v}_p \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \dots - \frac{\vec{v}_p \cdot \vec{v}_{p-1}}{\vec{v}_{p-1} \cdot \vec{v}_{p-1}} \vec{v}_{p-1} = \vec{v}_p - \sum_{i=1}^p \frac{\vec{v}_p \cdot \vec{v}_i}{\vec{v}_i \cdot \vec{v}_i} \vec{v}_i$$

Exercise:

The three vectors  $\vec{v}_1, \vec{v}_2$  and  $\vec{v}_3$  form a basis for subspace  $W$ , where

$$\vec{v}_1 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix}, \vec{v}_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \vec{v}_3 = \begin{pmatrix} 3 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

Suppose that an orthogonal basis for  $W$  is the set:

$$\{\hat{v}_1, \hat{v}_2, \hat{v}_3\}$$

Note that  $\vec{v}_1$  and  $\vec{v}_2$  are orthogonal. Therefore, to construct an orthogonal basis for  $W$ , we can set  $\hat{v}_1 = \vec{v}_1$  and  $\hat{v}_2 = \vec{v}_2$ . To determine  $\hat{v}_3$  we may use the Gram-Schmidt process. Find  $\hat{v}_3$ .

The projection of  $\vec{v}_3$  onto the space spanned by  $\vec{v}_1$  and  $\vec{v}_2$ ,  $W_2$ , is denoted by  $\text{proj}_{W_2} \vec{v}_3$ .

The difference between  $\vec{v}_3$  and its projection on  $W_2$  is in  $W$ , and is orthogonal to both  $\vec{v}_1$  and  $\vec{v}_2$ . So it is the vector that we need to compute.

$$\begin{aligned} \hat{v}_3 &= \text{proj}_{W_2} \vec{v}_3 = \vec{v}_3 - \frac{\vec{v}_3 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \frac{\vec{v}_3 \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2 \\ &= \vec{v}_3 - \frac{2}{2} \vec{v}_1 - \frac{4}{2} \vec{v}_2 = \vec{v}_3 - \vec{v}_1 - 2\vec{v}_2 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \end{aligned}$$

## TOPIC 2: The QR Factorization

Recall: DEFINITION

↳ A set of vectors form an orthonormal basis if the vectors are mutually orthogonal and have unit length.

Example: The two vectors below form an orthogonal basis for a subspace  $W$ . Obtain an orthonormal basis for  $W$ .

$$\vec{v}_1 = \begin{pmatrix} 3 \\ 2 \\ 0 \end{pmatrix}, \quad \vec{v}_2 = \begin{pmatrix} -2 \\ 3 \\ 1 \end{pmatrix}$$

$$\hat{v}_1 = \frac{1}{\sqrt{13}} \vec{v}_1, \quad \hat{v}_2 = \frac{1}{\sqrt{14}} \vec{v}_2$$

QR Factorization uses this concept.

### QR Factorization

Theorem:

Any  $m \times n$  matrix  $A$  with linearly independent columns has the QR factorization

$$A = QR$$

where:

\*  $Q$  is  $m \times n$ , its columns are an orthonormal basis for  $\text{Col } A$ .

\*  $R$  is  $n \times n$ , upper triangular, with positive entries on its diagonal.

Notes on QR Factorization:

\* We are not considering the case when  $A$  has linearly dependent columns.

\*  $Q$  can be obtained using the Gram-Schmidt process.

\* To obtain  $R$ , we use  $R = Q^T A$ , because

$$\begin{aligned} A &= QR \\ Q^T A &= Q^T QR \\ \underline{Q^T A = R} &\quad \because Q^T Q = I \end{aligned}$$

\* The length of the  $j$ th column of  $R$  is equal to the length of the  $j$ th column of  $A$ .

Example: Construct the QR decomposition for  $A = \begin{pmatrix} 3 & -2 \\ 2 & 3 \\ 0 & 1 \end{pmatrix}$

The columns of  $Q$  form an orthonormal basis for  $\text{Col } A$ , but the columns of  $A$  are already orthogonal (if they were not, we could use Gram-Schmidt).

Construct  $Q$  by dividing each column by its own length.

$$Q = \begin{pmatrix} \frac{3}{\sqrt{13}} & -\frac{2}{\sqrt{14}} \\ \frac{2}{\sqrt{13}} & \frac{3}{\sqrt{14}} \\ 0 & \frac{1}{\sqrt{14}} \end{pmatrix}$$

Next, we construct  $R$ .

$$R = Q^T A = \begin{pmatrix} \frac{3}{\sqrt{13}} & \frac{2}{\sqrt{13}} & 0 \\ -\frac{2}{\sqrt{14}} & \frac{3}{\sqrt{14}} & \frac{1}{\sqrt{14}} \end{pmatrix} \begin{pmatrix} 3 & -2 \\ 2 & 3 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} \sqrt{13} & 0 \\ 0 & \sqrt{14} \end{pmatrix} *$$

Exercise:

Suppose A is the matrix below.

$$A = \begin{pmatrix} 2 & 2 \\ 0 & 0 \\ 0 & 1 \end{pmatrix}$$

The columns of A are independent, so A has the QR Factorization

$$A = QR$$

where  $Q = \begin{pmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{pmatrix}$ , find R.

$$\begin{aligned} R &= Q^T A \\ &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 2 & 2 \\ 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 2 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} \end{aligned}$$